

## **Course Objectives**

- 1. Explain the function of controllers in a simple closed control loop model.
- 2. Define the terms: automatic to manual, manual to automatic, setpoint, tuning, direct acting, reverse acting, proportional band/gain, integral/reset, derivative/rate, and "bumpless" transfer.
- 3. Explain making setpoint adjustments on local and remote controllers.
- 4. Explain use of programmable logic controllers (PLC).
- 5. Explain use of distributed control systems (DCS).
- 6. Identify common controller drawings on P&IDs.

## **Key Terms** (Define the following)

Controllers
Drogrammable Logic Controller (DLC)
Programmable Logic Controller (PLC)
Distributed Control System (DCS)
Process equilibrium -
Dead time
Lag time -
Gain

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1







- 1. Pneumatic controllers typically are installed remotely.
  - □ True □ False
    - **False**
- 2. At a basic level, you need three things to control a process:
  - DCS, PLC, and a method for choosing the correct action
  - D Purpose, a set of controllers, and a method for choosing the correct action
  - Purpose, a set of choices, and a method for choosing the correct action
  - A set of controllers, a PLC, and a DCS
- 3. Comparing a measured variable to a set point to make controlled decisions is called
  - □ an open loop.
  - □ a closed loop.
- 4. describes the controlled variable signal cycling above or below the set point or exhibiting random behavior.
  - Oscillation
  - □ Hunting
  - Overshoot
  - □ Hysteresis
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